Evolving Spiking Neural P Systems

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Evolution + "learning"

- Evolution of human brain:
 - Likely started with basic sensory-motor control.
 - Add-on feature: "intelligence" and "learning" likely followed this basic control.
 - Learning followed, since evolution can only do so much...
- Spiking Neural Nets (or SNNs) are generalization of previous generation NNs:
 - Asynchronous (power efficient) and non-Von Neumann (processing and memory more linked together) etc.
 - Closer to bio-reality due to spikes, e.g. for interfacing robot arms to humans.
 - Many problems, e.g. less design consensus and theory than previous generation NNs.

SN P systems so far

- Many works on evolving *parameters* (e.g. synapse weight, firing delay) and *topology*, e.g.
- (1) Hebbian SN P systems.
- (2) SN P systems with neuron division and budding.
- (3) Optimization SN P systems.
- (4) SN P systems with plasticity
- (5) SN P systems with scheduled synapses
- (1), (2), (4), (5) involve "human designer";
- (3) involves evolutionary algorithm (or EA) to evolve parameters only:
 - One view of SNN: the topology is the algorithm.

Evolving SN P systems

• "Baby steps" to evolve (some) parameters and topology: An idea.



Evolving SN P systems





Evolving SN P systems

Ideas for *evolution paradigm*:

- Initially empty adjacency matrix of SN P:
- Proceed to add synapses, e.g.
 - No input neuron connects directly to an output neuron.
 - Each input neuron connects to at least one internal neuron (i.e. non-input or non-output neuron).
 - A neuron can only have either forgetting rules or spiking rules, but not both.
 - Each output neuron connects to exactly one internal neuron.
 - For feasibility, no dangling neurons, i.e. a path exists from any internal neuron to an output neuron.
- Repeat until stopping criterion is achieved.

Evolving SN P systems so far

- We have simulators, e.g. CPU, GPU, with rather efficient representations (e.g. *"sparse"* matrices, vectors).
- Some ideas for evolution of parameters and topology.
- Much work to be done, even with baby steps, e.g.
 - Experiments on hard problems, then later, real world problems.
 - Classify some problems (input-output) for some fixed parameters or topology (see evolution paradigm).
 - Response to perturbations, e.g. noise?
 - Classify some parameter or topology evolution for some fixed problems.
 - Evolve all synapses in the system? Subset?
 - Later: replacing EA with Oracle? Other ways to evolve?

- A bit of history:
 - Hubel & Wiesel experiment 1959, 1962, 1968



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- A bit of history:
 - Le-Net 1989
 - Gradient-based learning applied to document recognition [LeCun, Bottou, Bengio, Haffner 1998]



A Full Convolutional Neural Network (LeNet)

- A bit of history:
 - ImageNet Classification with Deep Convolutional Neural Networks [Krizhevsky, Sutskever, Hinton 2012]. Differences:
 - Use ReLu
 - It's deeper
 - Uses GPUs



Convolution Kernel







• A bit of history:

ImageNet: results for 2010-2014





Convolutional Nets galore!

- ConvNets are key in Deep Learning
 - Object detection & face detection
 - Image segmentation
 - Self-driving cars
 - Play Go & videogames
 - Speech & text processing
 - Generative: DeepDream
 - Read dreams

Lessons learned from Deep Learning

- GPUs were the **enabling technology**
 - Low-level library from NVIDIA: CuDNN
 - Specific hardware from Google came later
- Mature and end-user **tools**: TensorFlow, Caffe, Lasagne, Theano, CNTK, Keras ...
 - Large community and investment from important companies

Deep Learning: open problems

- What is going on inside the networks?
- Need too much data
- Don't extract meaning nor remember
 - Get me a knife = get me something to cut
- Supervised learning
- Need faster and more powerful machines
- (beyond deep learning and 3rd generation NN)

Thanks for the attention!

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