

Natural Computing with GPUs:

Accelerating Bioinspired Models with CUDA

David Orellana-Martín, Miguel Á. Martínez-del-Amor

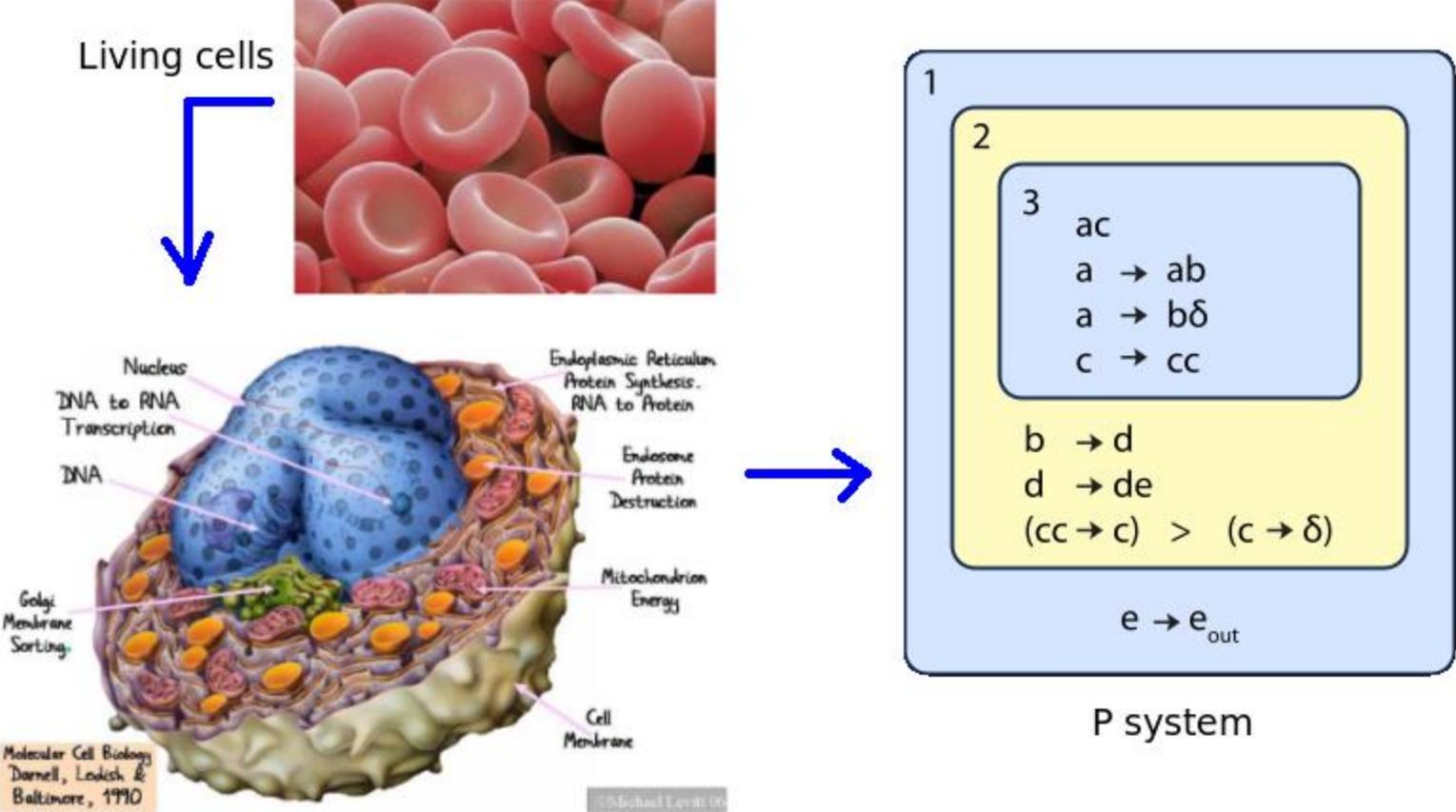
Research Group on Natural Computing

Universidad de Sevilla

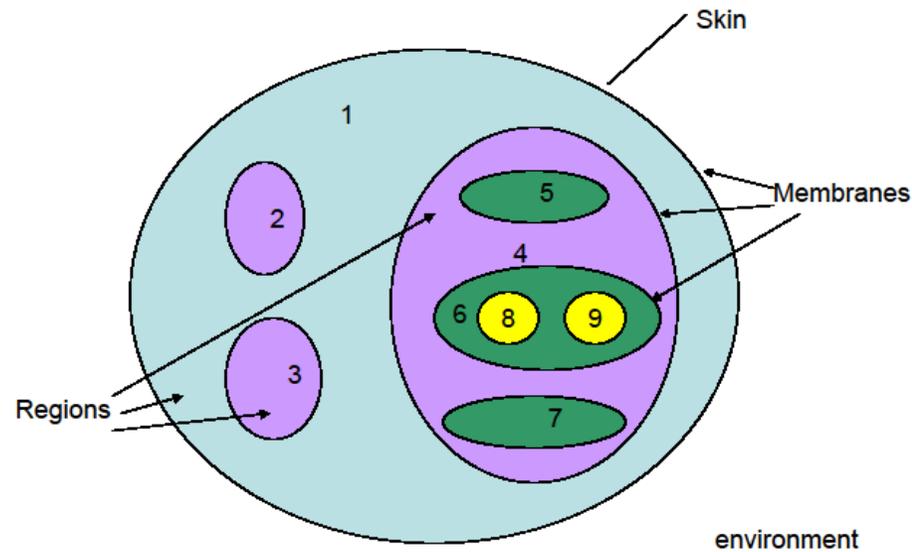
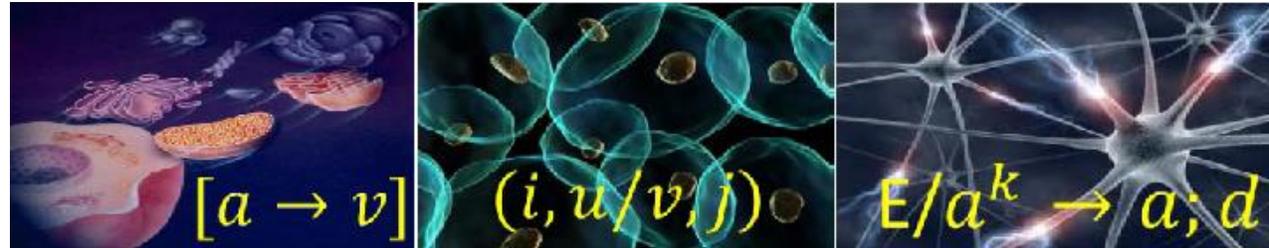
Outline

- Introduction to Membrane Computing
- Group trajectory with CUDA
- PMCGPU simulators
- Challenges

Membrane Computing

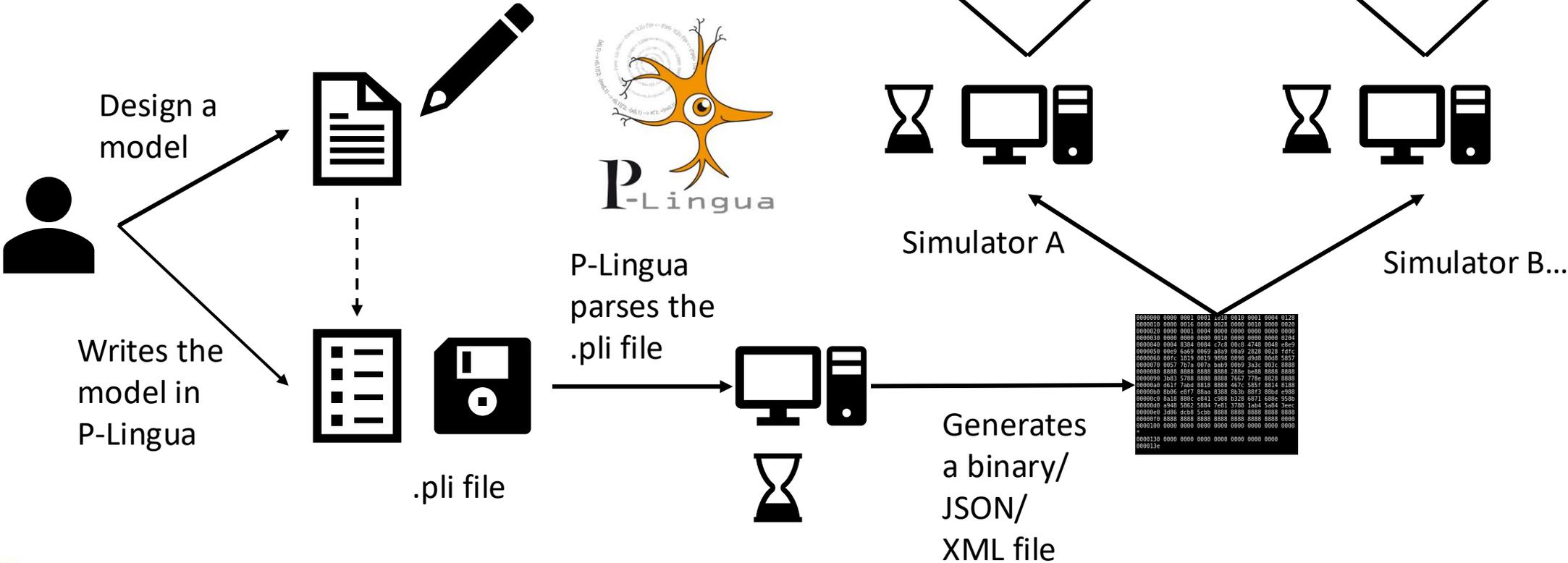


Membrane Computing



Membrane Computing

- P-Lingua 5 workflow:



Group trajectory with CUDA



(2009)
3xTesla C1060

BRIEFINGS IN BIOINFORMATICS, VOL. 9, NO. 3, 30-33
Advance Access published on 20 October 2009

Simulation of P systems with active membranes on CUDA

José M. Cecilia¹, José M. García², Ginés D. Guerrero³, Miguel A. Martínez-del-Amor¹, Ignacio Pérez-Hurtado and Mario J. Pérez-Jiménez

Abstract
P systems or Membrane Systems provide a high-level computational modelling framework that combines the structure and dynamic aspects of biological systems in a relevant and understandable way. They are inherently parallel and non-deterministic computing devices. In this article, we discuss the motivation, design principles and key of the implementation of a simulator for the class of recognizer P systems with active membranes running on a GPU. We compare our parallel simulator for GPUs to the simulator developed for a single central processing unit (CPU), showing that GPUs are better suited than CPUs to simulate P systems due to their highly parallel nature.

Keywords: natural computing, membrane computing, P Systems, parallel computing, GPU, CUDA

(2010)
Simulating P systems with active membranes solving SAT

Matrix Representation of Spiking Neural P Systems

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Abstract. Spiking neural P systems (SN P systems, for short) are a class of distributed parallel computing devices inspired from the way neurons communicate by means of spikes. In this work, a discrete structure representation of SN P systems with extended rules and without delay is proposed. Specifically, matrices are used to represent SN P systems. In order to represent the computations of SN P systems by matrices, configuration vectors are defined to monitor the number of spikes in each neuron at any given configuration; transition net gain vectors are also introduced to quantify the total amount of spikes consumed and produced after the chosen rules are applied. Nondeterminism of the systems is captured by a set of spiking transition vectors that could be used at any given time during the computation. With such matrix representation, it is quite convenient to determine the next configuration from a given configuration, since it involves only multiplication and addition of matrices after deciding the spiking transition vector.

(2011-12)
Simulating spiking neural P systems (Philippines)



(2009)
Simulating P systems with active membranes

Contents lists available at ScienceDirect
The Journal of Logic and Algebraic Programming
journal homepage: www.elsevier.com/locate/jlap

Simulating a P system based efficient solution to SAT by using GPUs

José M. Cecilia¹*, José M. García², Ginés D. Guerrero³, Miguel A. Martínez-del-Amor¹, Ignacio Pérez-Hurtado¹, Mario J. Pérez-Jiménez²

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ARTICLE INFO
Available online 24 April 2010

Keywords:
P systems
Membrane Computing
GPU

ABSTRACT
P systems are inherently parallel and non-deterministic, theoretical computing devices defined inside the field of Membrane Computing. Many P system simulations have been proposed in the past, but they are not very efficient since they cannot handle the parallelism of these devices. Nevertheless, by an interesting combination of the GPUs as a parallel hardware to compute general purpose applications, in this paper we analyze GPUs as an alternative parallel architecture to improve the performance in the simulation of P systems, and we illustrate this by using the case study of clearly ill-posed systems that provide an efficient solution to SAT by using P systems. We compare our parallel simulator for GPUs to the simulator developed for a single central processing unit (CPU), demonstrating that GPUs are well suited to simulate P systems. We also analyze the efficiency of the GPU architecture and we discuss the impact on the performance of the previous literature.

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(2010)
Matrix representation of spiking neural P systems (China-Philippines)

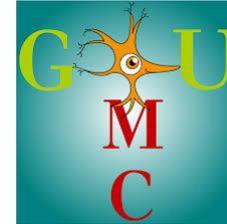


Group trajectory with CUDA

(2011)
GeForce
GTX550Ti



(2012)
Simulating
Population
Dynamics
P systems



(2013)
Miguel Á.
Martínez
del Amor
PhD Thesis



(2012)
GeForce
GTX780Ti

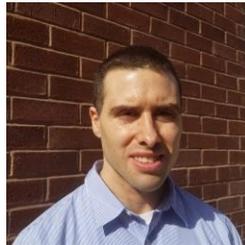


(2013)
PMCGPU
project

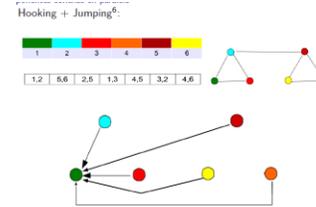


Group trajectory with CUDA

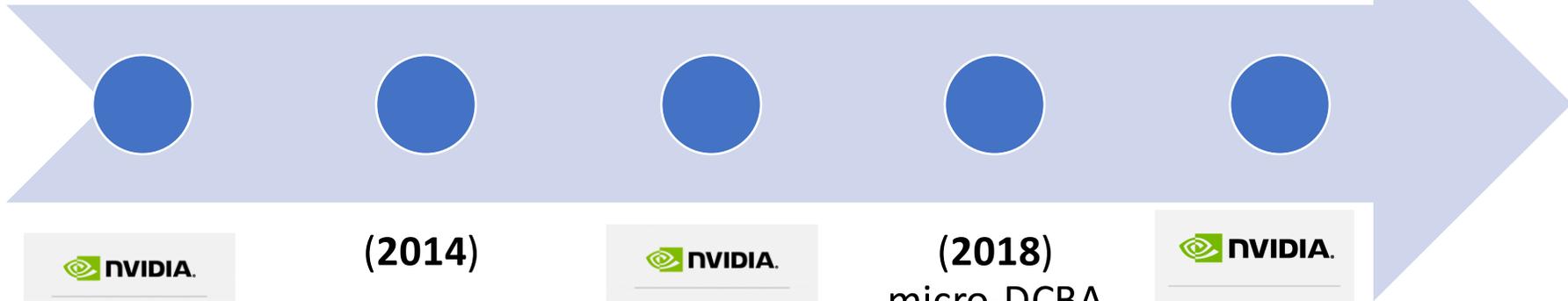
(2014)
NVIDIA
CUDA
Research
Center. K40
Donation



(2015)
NVIDIA
CUDA
Research
Center



(2018)
NVIDIA DLI
university
ambassador



(2014)
Manuel
García-
Quismondo
PhD Thesis



(2018)
micro-DCBA
for PDP
system
simulation



NVIDIA Spain meeting

Group trajectory with CUDA

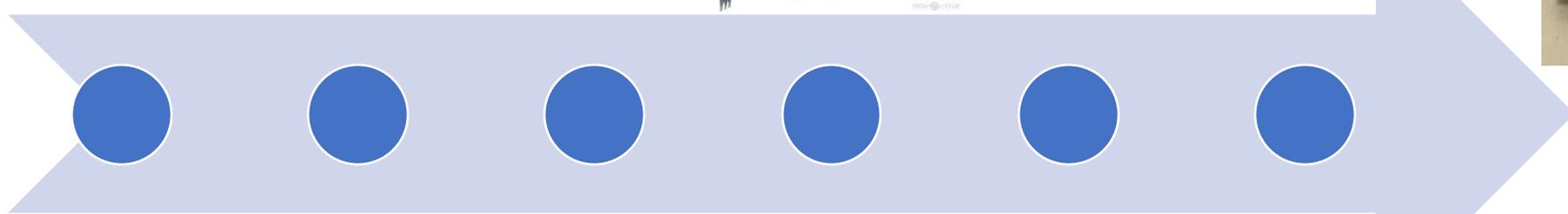
(2019)
2xRTX2080



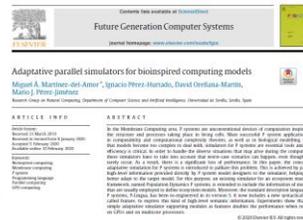
(2020)
Adaptative
simulation
of PDP
systems



(2021)
NVIDIA
Hardware
grant.
A100



(2019)
Daniel
Campora
PhD Thesis



(2021)
3xRTX3090



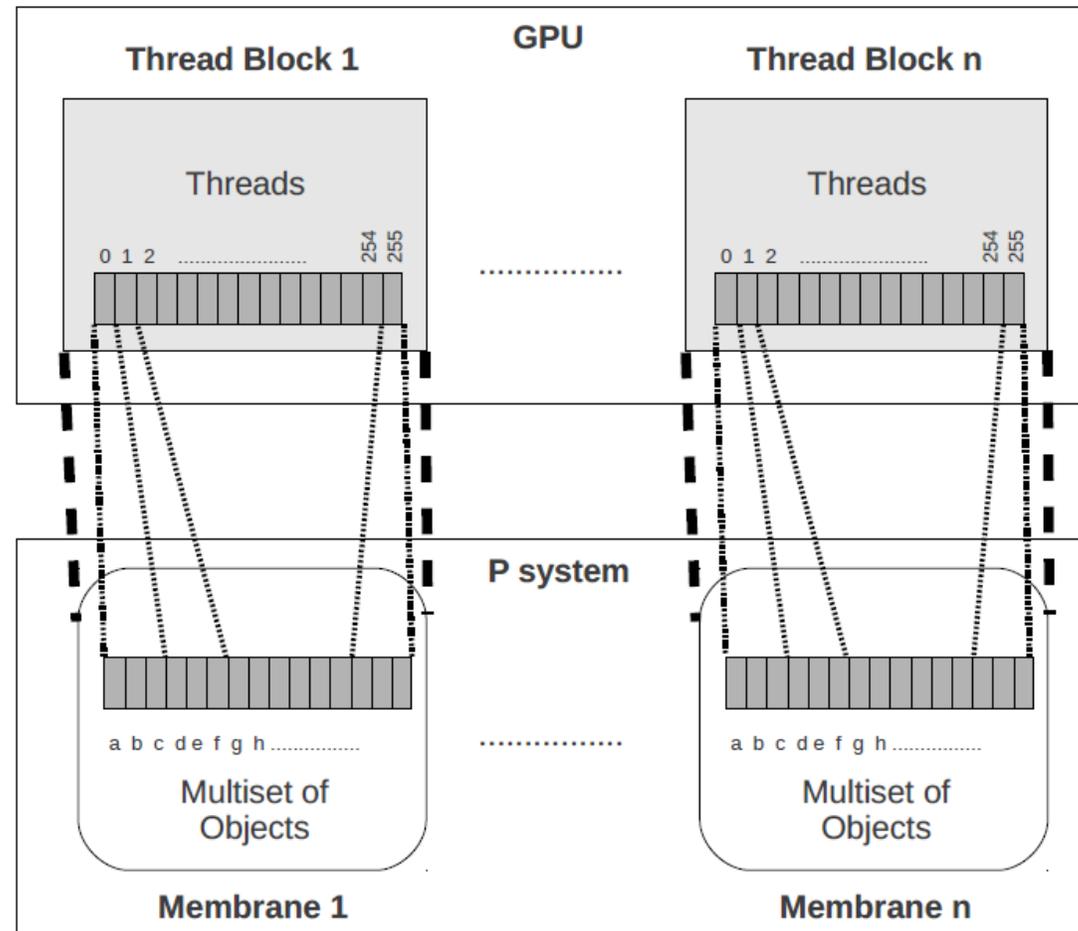
(2024)
Sparse
simulation
of Spiking
Neural P
systems

NVIDIA University Ambassador

- Miguel Ángel Martínez-del-Amor, nominated in 2018
- Certificated instructor for:
 - Fundamentals of Accelerated Computing with Modern CUDA ++
 - Fundamentals of Deep Learning
 - Fundamentals of Accelerated Data Science
- Interested in:
 - Simulation of artificial neural networks, with emphasis on efficiency (sparsity & quantization)
 - Transferring concepts to spiking neural P systems and other natural computing models

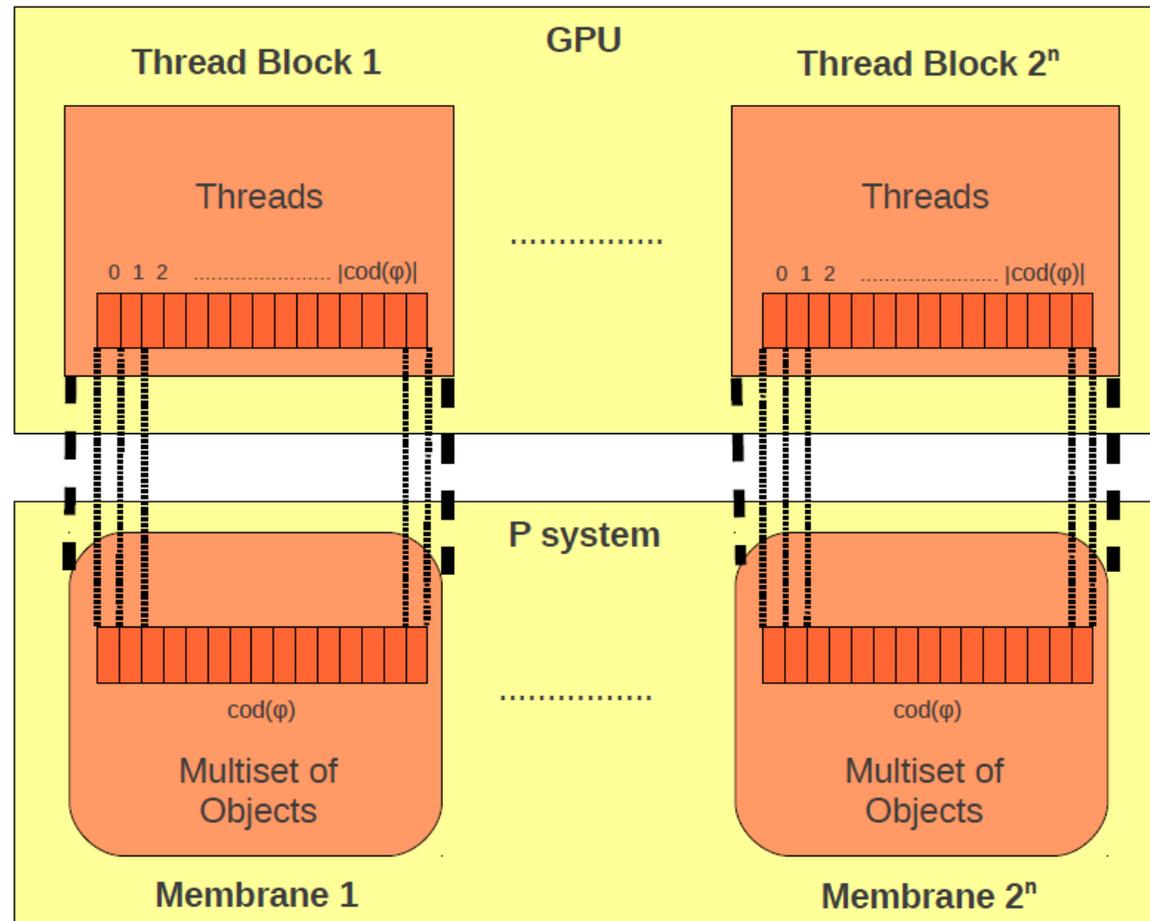
Parallelism schema of P systems

- P systems with active membranes



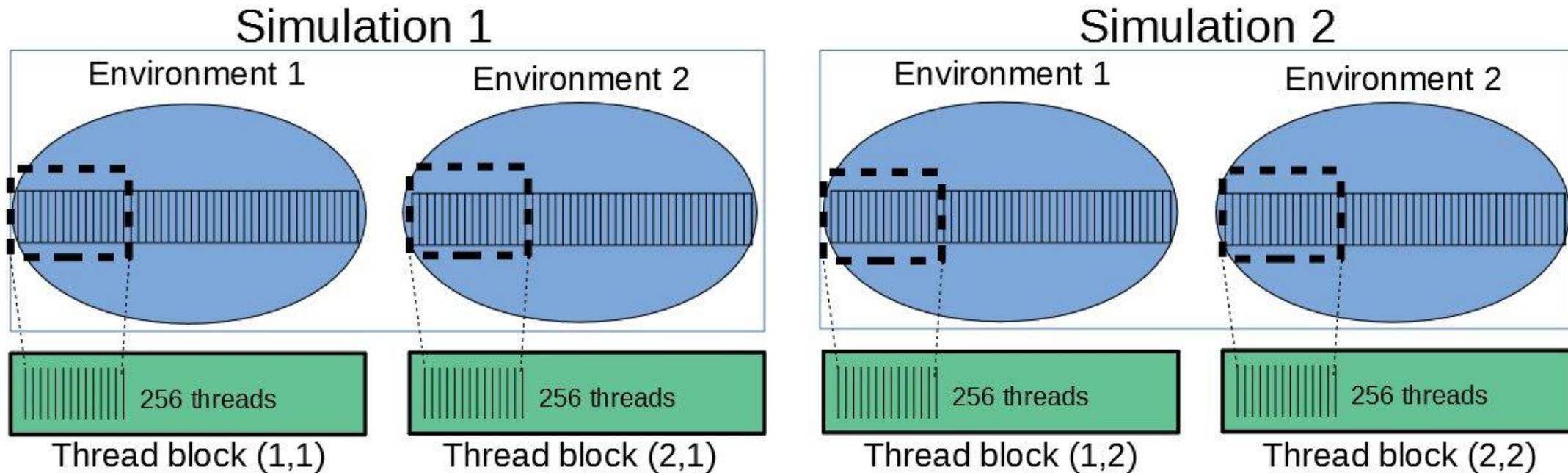
Parallelism schema of P systems

- Solution to SAT by P systems with active membranes



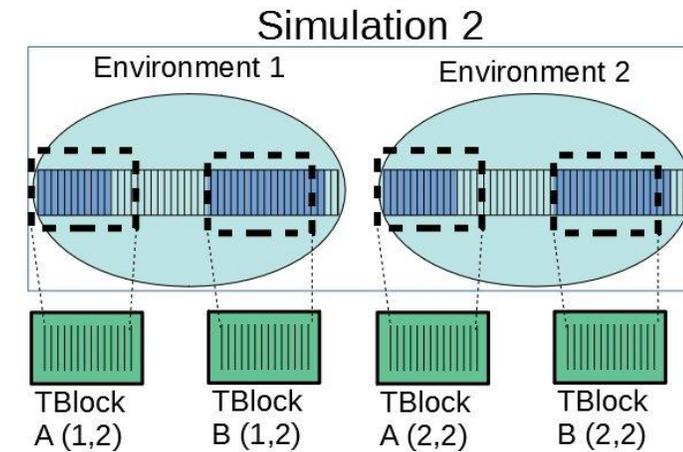
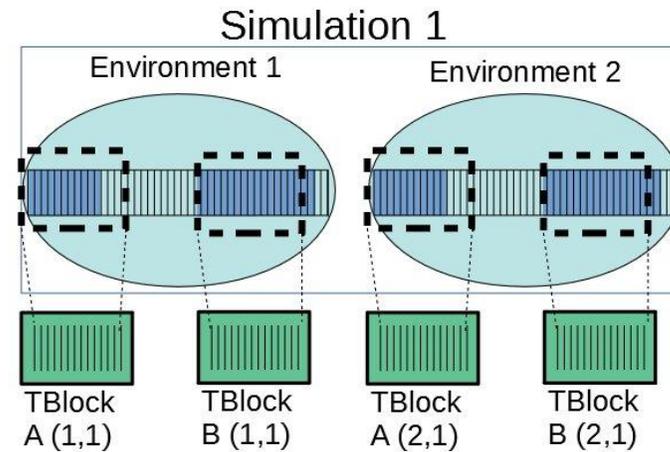
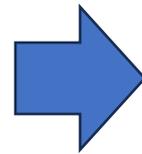
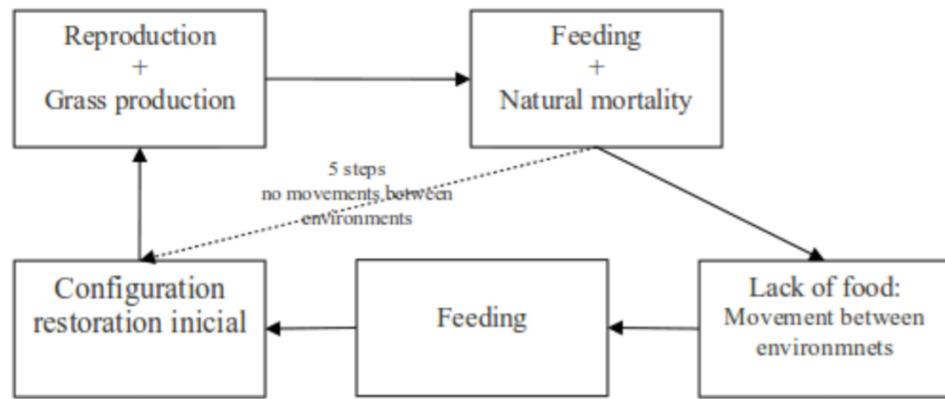
Parallelism schema of P systems

- Population Dynamic P (PDP) systems



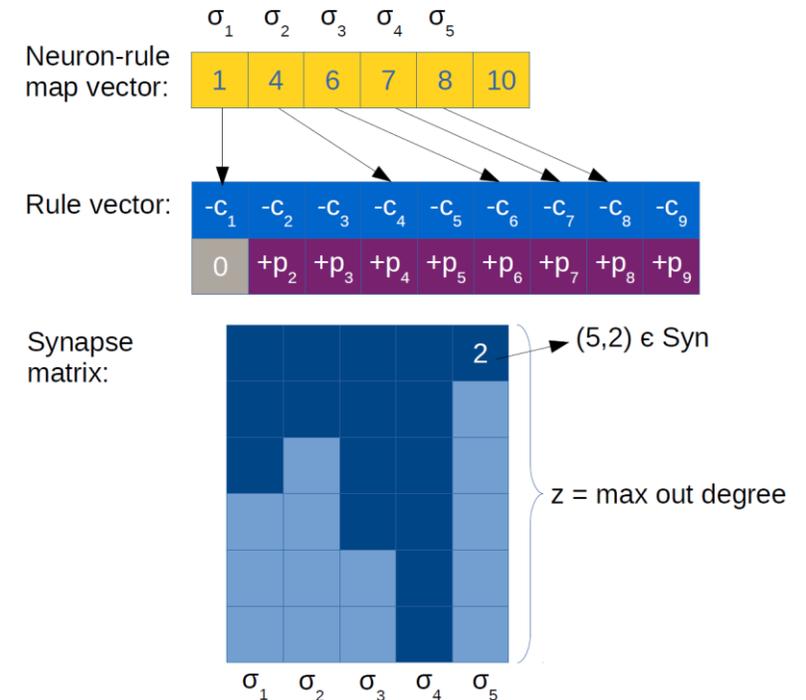
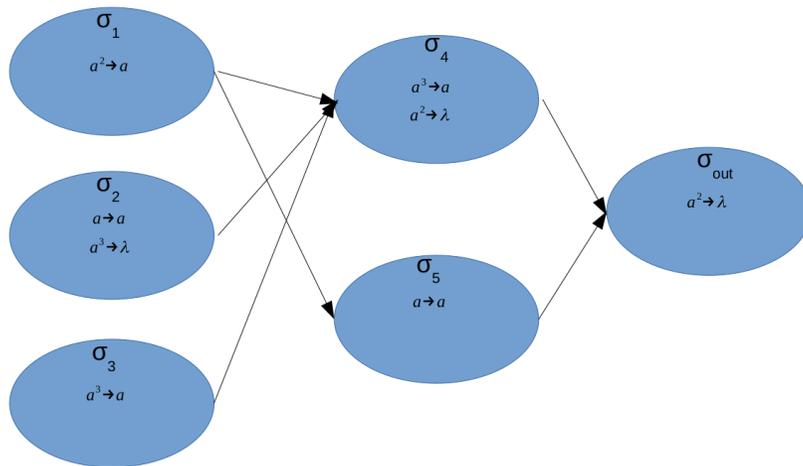
Parallelism schema of P systems

- Population Dynamic P (PDP) systems (Adaptative)



Parallelism schema of P systems

- Sparse representation of Spiking Neural P systems

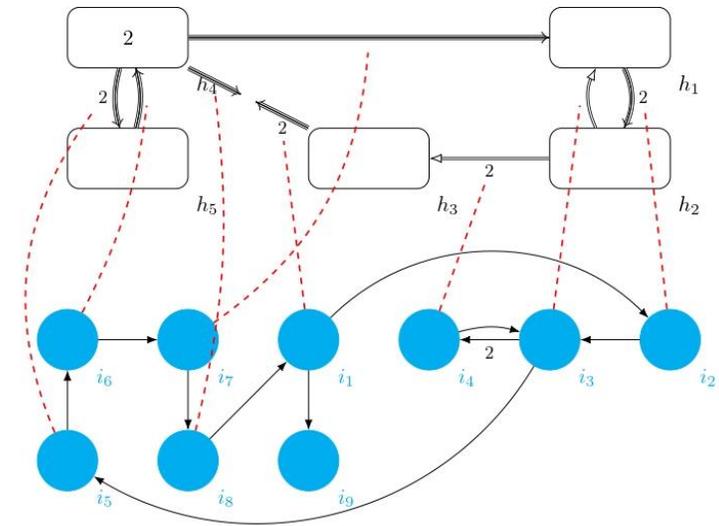
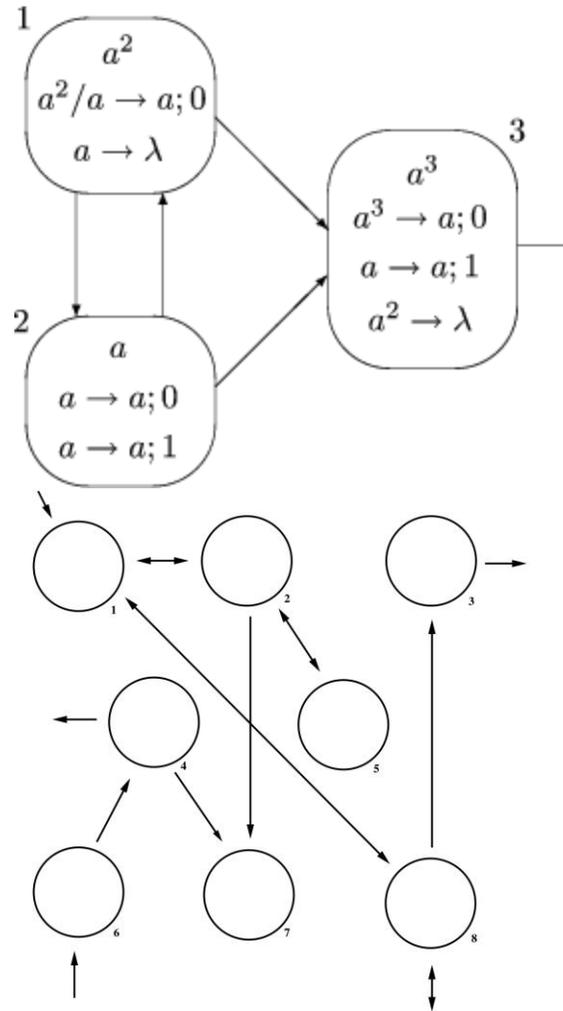
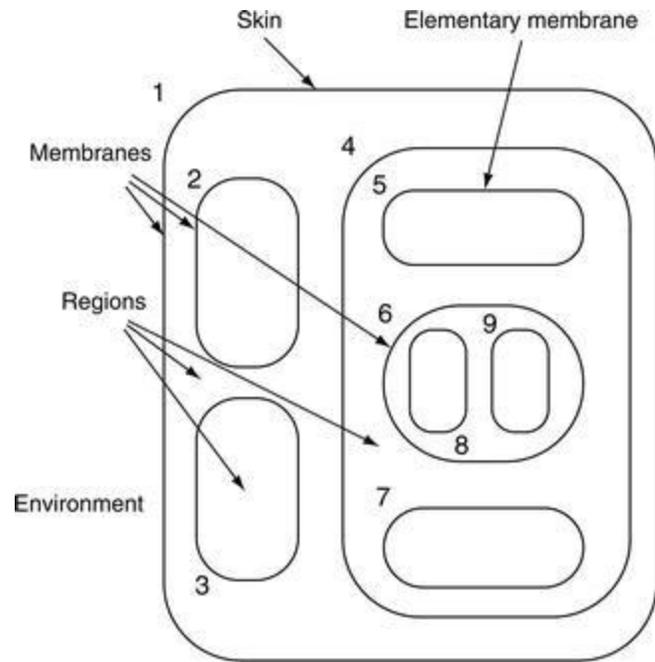


Summary of results

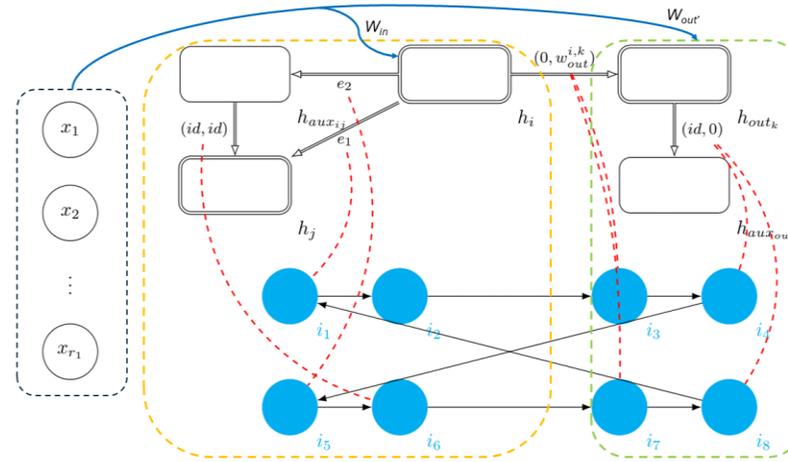
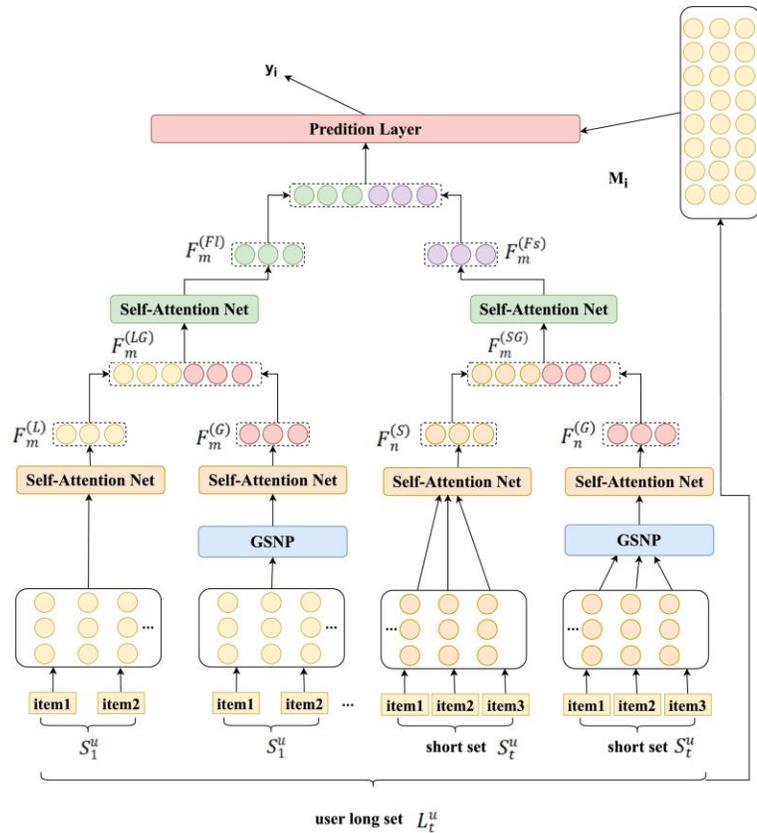
Simulator Codename	P system model and coverage	Peak speedup	GPU tested
PCUDA	(G) Active membranes	7x (T) 1.67x (R)	C1060
PCUDASAT	(S) Active membranes	63x (R)	C1060
TSPCUDASAT	(S) Tissue w/ cell division	10x (R)	C1060
ABCDGPU	(G) Population Dynamics	18.1x (T) 5x (R)	K40
ENPS-GPU	(G) Enzymatic Numerical	10x (T)	GTX460M
CuSNP	(G) Spiking Neural	50x (R)	GTX750

G= Generic, S=Specific, T=Stress testing, R=Real examples.

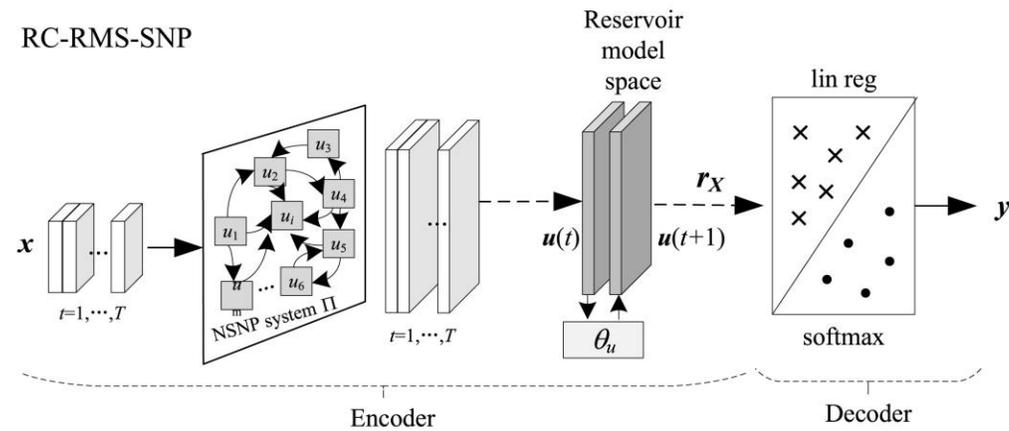
Current work on artificial intelligence



Current work on artificial intelligence

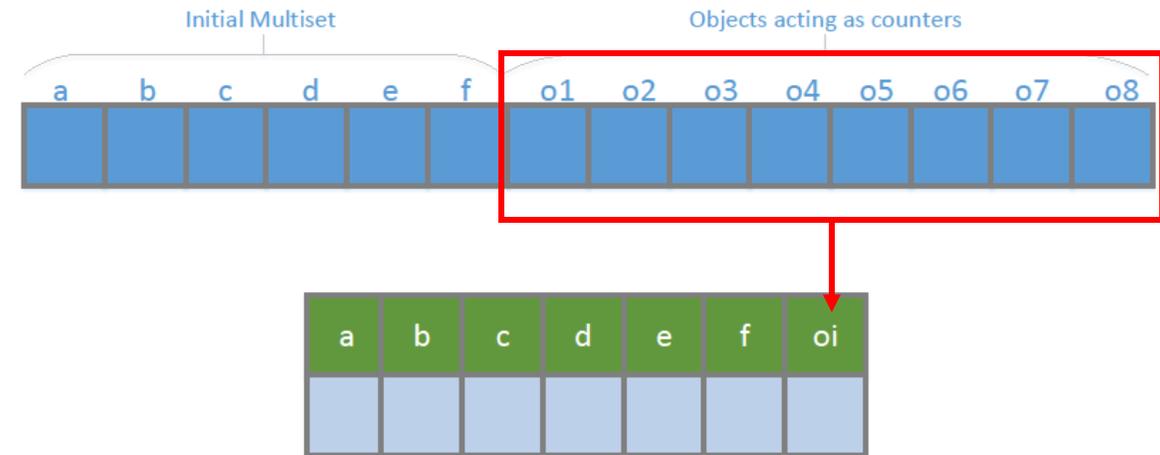
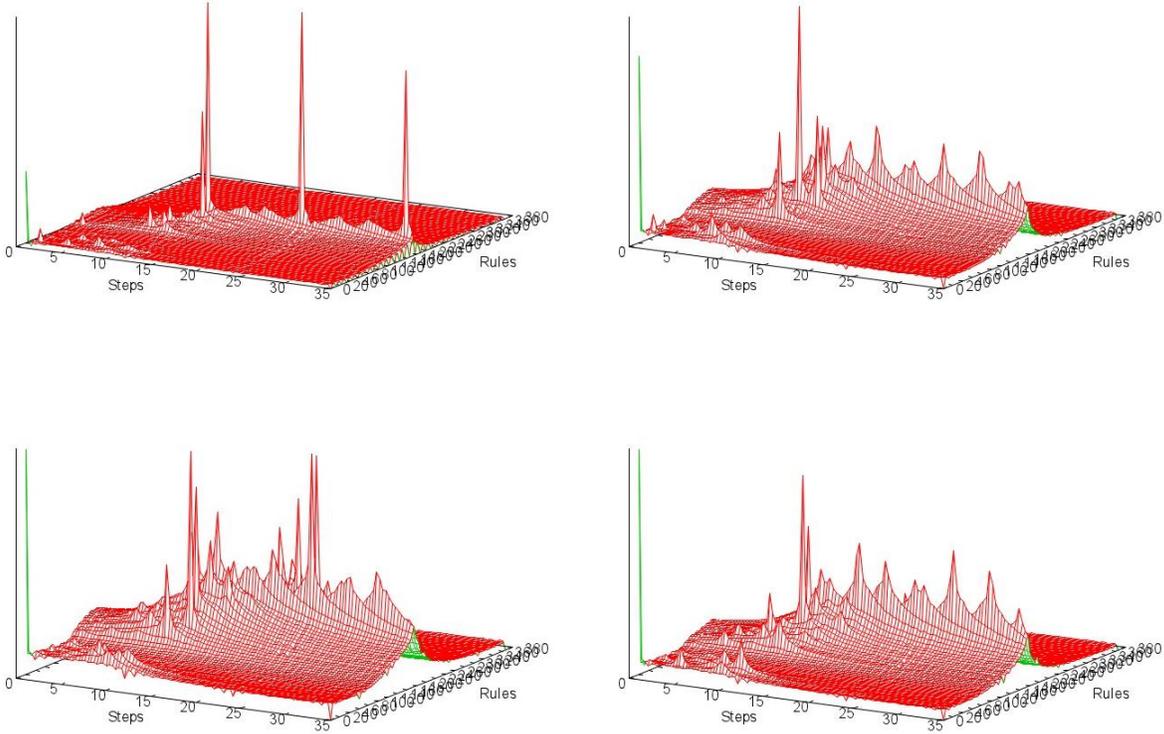


RC-RMS-SNP



Challenges

- Sparse designs (different objects as counters)



Challenges

- Developing calibrator for model parameters
- Supporting new spiking neural P systems models used for deep learning
- Development from Python
- Multi-GPU models

Thank you very much!