Characterizing the Aperiodicity of Irreducible Markov Chains by Using P Systems

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Summary. It is well known that any irreducible and aperiodic Markov chain has exactly one stationary distribution, and for any arbitrary initial distribution, the sequence of distributions at time n converges to the stationary distribution, that is, the Markov chain is approaching equilibrium as $n \to \infty$.

In this paper, a characterization of the aperiodicity in existential terms of some state is given. At the same time, a P system with external output is associated with any irreducible Markov chain. The designed system provides the aperiodicity of that Markov chain and spends a polynomial amount of resources with respect to the size of the input. A formal verification of this solution is presented and a comparative analysis with respect to another known solution is described.

1 Introduction

A discrete-time Markov chain is a stochastic process such that the past time is irrelevant to predict the future, given knowledge of the present time. That is, given the present time, the future does not depend on the past time: the result of each event depends only on the result of the previous event.

In order to study the evolution in time of a Markov chain as well as the existence of the stationary distribution, it is suitable to classify its states. This classification depends on the path structure of the chain.

One of the central issues in Markov Theory is the study of the asymptotic behavior of Markov chains. It is well known that for any irreducible and aperiodic Markov chain: (a) there exists at least one stationary distribution (that is, a probability distribution on the state space which is an invariant for the transition

matrix associated with the chain), and (b) for any initial distribution, $\mu^{(0)}$ and for any stationary distribution π for the Markov chain, the sequence $(\mu^{(n)})_{n \in \mathbb{N}}$ converges to π in total variation as $n \to \infty$ (that is, the Markov chain is approaching equilibrium as $n \to \infty$).

In the paper [2], a classification of states of a finite and homogeneous Markov chain is provided by using P systems. Moreover, the period was calculated for recurrent classes. The design of the P systems was inspired in properties used in classic algorithms that deal with the problem of the classification. Especially, this solution allows us to decide whether an irreducible Markov chain is aperiodic or not.

The main goal of this paper is to design a P system associated with an irreducible Markov chain which provides an answer to the aperiodicity of the chain. If the answer is negative, then the system provides the period of the chain. The solution presented is based on a characterization of the aperiodicity in existential terms of some state and a natural number, and it is *semi-uniform*, in the sense that for each Markov chain, a P system associated with it is constructed. Besides, the solution spends a polynomial amount of resources in the sense of the computational complexity theory in Membrane Computing.

The solution presented in the paper improves the solution obtained in [2], because less computational resources are used.

The paper is organized as follows. In the following section, we recall some basic notions and results that we use in the paper. In Section 3, a P system associated with an irreducible Markov chain is designed in order to study the periodicity of that class. Section 4 shows a formal verification of the designed P system. In Section 5, the solution presented is compared with another solution obtained from [2]. Finally some conclusions are presented.

2 Preliminaries

A discrete Markov chain is a sequence $\{X_t \mid t \in \mathbb{N}\}$ of random variables whose values are called *states*, that verifies the following property:

$$P(X_{t+1} = j/X_0 = i_0, X_1 = i_1, \dots, X_t = i_t) = P(X_{t+1} = j/X_t = i_t)$$

Without loss of generality, we can suppose that the state space is the set of nonnegative integers.

The value of variable X_t is interpreted as the state of the process at instant t. In this paper we work with Markov chains having a finite state space $S = \{s_1, \ldots, s_k\}$.

A discrete Markov chain is characterized by the *transition probability*

$$p_{ij}(t) = P(X_t = s_j / X_{t-1} = s_i), \ \forall t \ge 1$$

where $p_{ij}(t)$ provides the transition from state s_i to state s_j at time t-1. The matrix of transition probabilities

$$P(t) = (p_{ij}(t))_{1 < i,j < k}$$

is a stochastic matrix, that is, is nonnegative for all t and the sum of each arrow is equal to $1, \sum_{j=1}^{k} p_{ij}(t) = 1$.

We say that the chain is time homogeneous or stationary if $p_{ij}(t) = p_{ij}$ for each t and it verifies the Kolmogorov-Chapman equation:

$$p_{ij}^{(1)} = p_{ij}, \quad p_{ij}^{(2)} = \sum_{l=1}^{k} p_{il} p_{lj}, \quad \dots, \quad p_{ij}^{(n)} = \sum_{l=1}^{k} p_{il} p_{lj}^{(n-1)},$$

where $p_{ij}^{(n)}$ is the transition probability of state s_i to state s_j at time n. We denote the initial distribution by means of the vector

$$\mu^{(0)} = (\mu_1^{(0)}, \dots, \mu_k^{(0)}) = (P(X_0 = s_1), P(X_0 = s_2), \dots, P(X_0 = s_k))$$

and the distribution of the Markov chain at time n is

$$\mu^{(n)} = (\mu_1^{(n)}, \dots, \mu_k^{(n)}) = (P(X_n = s_1), P(X_n = s_2), \dots, P(X_n = s_k))$$

Then, $\mu^{(n)} = \mu^{(0)} \cdot P^{(n)}$, where $P = (p_{ij})$ is the transition matrix of the homogeneous Markov chain.

Next, we introduce some concepts and results related to the states of a homogeneous Markov chain.

We say that a state s_j communicates with another state s_i (and we denote it by $s_i \to s_j$), if there exists a natural number n > 0 such that $p_{ij}^{(n)} > 0$ (that is, if the chain has a positive probability of ever reaching s_j when we start from s_i . We say that the states s_i and s_j intercommunicate (and we denote it by $s_i \leftrightarrow s_j$) if $s_i \to s_j$ and $s_j \to s_i$.

In the finite state space $S = \{s_1, \ldots, s_k\}$ of a Markov chain, the relation \leftrightarrow is an equivalence relation and we can consider the corresponding quotient set $\{s_1, \ldots, s_k\}/ \leftrightarrow$ whose elements are the classes of equivalence by \leftrightarrow .

A Markov chain with state space $S = \{s_1, \ldots, s_k\}$ is said to be *irreducible* if there exists only one class of equivalence by \leftrightarrow ; that is, if for all $s_i, s_j \in E$ we have $s_i \leftrightarrow s_j$. Otherwise, the chain is said to be *reducible*.

We say that a state s_i is *recurrent* or *essential* if for each natural number m and for each state s_j verifying $p_{ij}^{(m)} > 0$ there exists a natural number n such that $p_{ji}^{(n)} > 0$. Otherwise, the state is said to be *transient*. A recurrent class is the equivalence class determined by a recurrent state.

It is easy to prove that from a recurrent state, only recurrent states belonging to the same class are reachable.

A recurrence time of s_i is a natural number n > 0 such that $p_{ii}^{(n)} > 0$. The period of a state s_i is defined as $d(i) = \text{g.c.d.} \{n \ge 1 \mid p_{ii}^{(n)} > 0\}$, that is, it is the greatest common divisor of the recurrence times associated with it. All states belonging to the same class have the same period.

Then, we can define the period of a class of a given Markov chain in a natural manner: it is the period of any state of the class (see [3] and [4] for more details).

Definition 1. A Markov chain is said to be aperiodic if all its states are aperiodic; that is, their periods are equal to 1. Otherwise, the chain is said to be periodic.

Next, we provide a method to compute the period of a recurrent class and a characterization of the periodicity of a class.

Theorem 1. Let $A = \{s_1, \ldots, s_r\}$ be a recurrent class. The period of A is

$$d = g.c.d. \{n \mid p_{ii}^{(n)} > 0; \ 1 \le i, n \le r\}$$

That is, the period of A is the greatest common divisor of all times of recurrences of the states of that class, smaller than or equal to r.

Proof. By definition, given a state s_i $(1 \le i \le r)$ its period is

$$d(i) = g.c.d. \{ n \ge 1 \mid p_{ii}^{(n)} > 0 \}$$

As all states have the same period d, we have

$$d = d(1) = d(2) = \ldots = d(r) = g.c.d. \ \{n \ge 1 \mid p_{ii}^{(n)} > 0; \ 1 \le i \le r\}.$$

Let $d' = g.c.d.\{n \mid p_{ii}^{(n)} > 0; 1 \le i, n \le r\}$. Let us see that d = d'. For that, we will check that any trajectory from a state $s_i \in A$ to itself, with the length bigger than r, is the composition of trajectories with length smaller than or equal to r between the same states.

Let n > r be a time of recurrence associated with a state $s_i \in A$, that is, $p_{ii}^{(n)} > 0$. There exists a state s_{i_0} such that $p_{ii}^{(n)} \ge p_{ii_0}^{(n')} \cdot p_{i_0i_0}^{(no')} \cdot p_{i_0i_0}^{(n'')} > 0$, being $n = n' + n_0 + n''$. Thus, n_0 and n' + n'' are also times of recurrence.

If $n_0 > r$ or n' + n'' > r, then we repeat the process until we obtain a decomposition

$$p_{ii}^{(n)} \ge p_{ii_0}^{(n')} \cdot p_{i_0i_0}^{(n_0)} \cdot p_{i_1i_1}^{(n_1)} \dots p_{i_ri_r}^{(n_r)} \cdot p_{i_ri}^{(n'')} > 0$$

with $1 \le i_1, ..., i_r \le r$, $n = n' + n_1 + ... + n_r + n''$ verifying $n' + n'' \le r$ and $n_1, ..., n_r \le r$.

Finally, let us notice that substituting $p_{ii}^{(n)}$, with n > k, by a *suitable* sequence of $p_{ii}^{(m)}$, with $m \le k$, the g.c.d. is the same.

Lemma 1. Let $A = \{a_1, \dots, a_r\}$ be a set of natural numbers. Let us suppose g.c.d. $\{a_1, \dots, a_r\} = 1$. Let us denote by A^+ the set of all positive linear combinations

 $\lambda_1 a_1 + \cdots, \lambda_r a_r, \quad with \quad \lambda_i \in Z^+, 1 \le i \le r.$

Then, there exists a natural number N such that $n \in A^+$ for all $n \ge N$.

Proof. See, e.g., the appendix of [1]

Next, we characterize the aperiodicity of a recurrent class of a finite Markov chain through the existence of a state s_i reachable from each state s_i .

Theorem 2. Let $\{X_t \mid t \in \mathbb{N}\}$ be a Markov chain with state space $S = \{s_1, \ldots, s_k\}$ and transition matrix $P = (p_{ij})$.

- (1) If $\{X_t \mid t \in \mathbb{N}\}$ is aperiodic, then there exists a natural number N such that $p_{ii}^{(n)} > 0$, for all $i \ (1 \le i \le k)$ and all $n \ge N$.
- (2) If $\{X_t \mid t \in \mathbb{N}\}$ is irreducible and aperiodic, then there exists a natural number M such that $p_{ij}^{(n)} > 0$, for all i, j $(1 \le i, j \le k)$ and all $n \ge M$.

Proof. See, e.g., Chapter 4 from [3]

Theorem 3. Let $A = \{s_1, \ldots, s_r\}$ be a recurrent class of a finite Markov chain. The following are equivalent:

- (1) Class A is aperiodic.
- (2) There exists a state $s_i \in A$ and a natural number $m_0 \in \mathbb{N}$ such that $p_{ij}^{(m_0)} > 0$ for all state $s_i \in A$.

Proof. Let us suppose that class A is aperiodic. Then all states in A have the same period d = 1. From Theorem 2 there exists a natural number N such that $p_{ii}^{(n)} > 0$, for all $i \ (1 \le i \le r)$ and all $n \ge N$. Given $j \ (1 \le j \le r)$, we define $n_i(j) = \min\{n \mid p_{ij}^{(n)} > 0\}$, for each $s_i \in A$, $n(j) = \max\{n_1(j), \dots, n_r(j)\}$, and $m_i(j) = \min\{n \mid p_{ij} > 0\}$, for each $s_i \in A$, $n(j) = \max\{n_1(j), \dots, n_r(j)\}$, and $m_0 = N + n(j)$. Let us see that $p_{ij}^{(m_0)} > 0$, for each i $(1 \le i \le r)$. We have $p_{ij}^{(m_0)} \ge p_{ij}^{(n_i(j))} p_{jj}^{(m_0 - n_i(j))} > 0$ because of $p_{ij}^{(n_i(j))} > 0$ by definition of $n_i(j)$, and $p_{jj}^{(m_0 - n_i(j))} > 0$ by Theorem 2. Conversely, let us suppose that there exists $m_0 \ge 1$ and a state $s_j \in A$ such that $\forall s_i \in A$ we have $p_{ij}^{(m_0)} > 0$. In particular, $p_{jj}^{(m_0)} > 0$ so m_0 is a recurrence time. On the one hand, if d is the period of the class, then m_0 is a multiple of d. On

the other hand, if $s_i \in A$ is a state such that $p_{ji} > 0$, then $0 < p_{ij}^{(m_0)} p_{ji} \le p_{ii}^{(m_0+1)}$ so $m_0 + 1$ is a multiple of d. Hence, d = 1.

3 A P System Associated with an Irreducible Markov Chain

The goal of this paper is to study the aperiodicity of an irreducible Markov chain with state space $S = \{s_1, \ldots, s_k\}, k \geq 2$, by using P systems. In the affirmative case, the answer of the system is YES, on the contrary, the system sends an object encoding the period of the class to the environment.

3.1 The Design of the P System

Let $P_k = (p_{ij})_{1 \le i,j \le k}$ be a Boolean matrix associated with a class with a finite and homogeneous Markov chain of order k such that $p_{ij} = 1$ if the transition from s_i to s_j is possible, and $p_{ij} = 0$ otherwise; that is, P_k is the adjacency matrix of the directed graph associated with the recurrent class.

The solution presented in this paper is a *semi–uniform* one in the following sense: we give a family $\mathbf{\Pi} = \{\Pi(P_k) \mid k \in \mathbf{N}\}$, associating with P_k a P system with external output, such that:

- There exists a deterministic Turing machine working in polynomial time which constructs the system $\Pi(P_k)$ from P_k .
- The output of the P system $\Pi(P_k)$ provides the classification of the recurrent class of the Markov chain as well as the period of the states.

We associate with the matrix P_k the P system of degree 4 with external output,

 $\Pi(P_k) = (\Gamma(P_k), \mu(P_k), \mathcal{M}_1, \mathcal{M}_2, \mathcal{M}_3, \mathcal{M}_4, R)$

defined as follows:

• Working alphabet:

$$\begin{split} \Gamma(P_k) &= \{s_{ij}, \ t_{ij}, \ \tau_{ij} \mid 1 \le i, j \le k\} \ \cup \{s_{ijr} \mid 1 \le i, j, r \le k\} \cup \\ \{T_r \mid 0 \le r \le k\} \ \cup \{\beta_l \mid 0 \le l \le k-1\} \cup \{b_i \mid 1 \le i \le k\} \cup \\ \{p_r \mid 1 \le r \le k\} \ \cup \ \{c_i, \ d_i \mid 0 \le i \le \alpha\} \cup \{yes, YES, \sigma, \} \end{split}$$

where $\alpha = 3k + \lceil \frac{k}{2} \rceil$.

In the working alphabet the objects:

- s_{ii} represents (at the initial configuration) the state s_i of the chain.
- t_{ij} and τ_{ij} represent the elements p_{ij} of the Boolean matrix associated with the transition matrix of the Markov chain.
- s_{ijr} represents the existence of a path of length r from the state s_i to state s_j .
- T_r and p_r represent the existence of a recurrence time equal to r in different configurations.

 τ_{ij} represents that the state s_j is reachable from state s_i .

- Membrane structure: $\mu(P_k) = [[[]_1]_2]_3]_4.$
- Initial multisets:

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$$\mathcal{M}_{1} = \{t_{ij}^{p_{ij}} \mid 1 \le i, j \le k\} \cup \{\beta_{0}\} \\ \mathcal{M}_{2} = \{s_{ii} \mid 1 \le i \le k\} \\ \mathcal{M}_{3} = \{b_{i} \mid 1 \le i \le k\} \cup \{d_{0}\} \\ \mathcal{M}_{4} = \emptyset$$

• The set R of evolution rules consists of the following rules:

$$\begin{aligned} r_1(ij) &\equiv [t_{ij} \to \tau_{ij} t_{ij}^k]_1, \quad 1 \le i, j \le k \\ r_2(i) &\equiv [\beta_i \to \beta_{i+1}]_1, \quad 0 \le i \le k-2 \\ r_3 &\equiv [\beta_{k-1}]_1 \to c_0^k \\ r_4(rij) &\equiv [c_r s_{ij} \tau_{j1}^{p_{j1}} \dots \tau_{jk}^{p_{jk}}]_2 \to [s_{i1}^{p_{j1}} \dots s_{ik}^{p_{jk}} c_{r+1}^{\gamma_j}]_2 s_{i1r+1}^{p_{j1}} \dots s_{ikr+1}^{p_{jk}} T_{r+1}^{p_{ji}}, \\ 1 \le i, j \le k, \quad 0 \le r \le \alpha - 1, \gamma_j = \sum_{l=1}^k p_{jl} \end{aligned}$$

$$\begin{split} r_{5} &\equiv [\sigma]_{2} \to \sigma \\ r_{6}(jr) &\equiv [s_{1jr} \dots s_{kjr}]_{3} \to [\sigma]_{2} \ yes, \quad 1 \leq j \leq k, \ 1 \leq r \leq \alpha \\ r_{7}(r) &\equiv [T_{r}b_{r} \to p_{r}]_{3}, \quad 1 \leq r \leq k \\ r_{8}(il) &\equiv [p_{i}p_{i+l} \to p_{i}p_{l}]_{3}, \quad 1 \leq i \leq k, \ 1 \leq l \leq k-i \\ r_{9}(i) &\equiv [p_{i}^{2} \to p_{i}]_{3}, \quad 1 \leq i \leq k \\ r_{10}(i) &\equiv [d_{i} \to d_{i+1}]_{3}, \quad 0 \leq i \leq \alpha - 1 \\ r_{11}(r) &\equiv [d_{\alpha}p_{r}]_{3} \to p_{r}[\]_{3}, \quad 2 \leq r \leq k \\ r_{12} &\equiv [d_{\alpha}p_{1}]_{3} \to yes[\]_{3} \\ r_{13} &\equiv [yes]_{4} \to YES[\]_{4} \\ r_{14}(r) &\equiv [p_{r}]_{4} \to p_{r}[\]_{4}, \quad 1 \leq r \leq k \end{split}$$

3.2 An Overview of Computations

Initially, membrane 1 contains objects t_{ij} that codify the elements p_{ij} of the Boolean matrix associated with the transition matrix of the Markov chain, together with the counter β_0 . This counter allows us to dissolve membrane 1 at a certain instant. Membrane 2 contains initially objects s_{ii} that codify the states s_i of the chain. Membrane 3 contains objects b_i that will be used in order to avoid that repeated recurrence times smaller than or equal to k appear. The counter d in membrane 2 will be used to trigger the answer at the suitable instant.

The design of the P system $\Pi(P_k)$ implements a process that is structured by stages. The first one consists of k steps which allow the production of sufficiently many new copies τ_{ij} of objects t_{ij} . This is done by applying rules of type r_1 and r_2 in membrane 1 at k-1 first steps and applying at step k rule r_3 that dissolves membrane 1.

At the second stage, all paths between states with length at most k, as well as recurrence times smaller than or equal to k, are generated. This stage starts at step k + 1 and it spends at most k steps. First, rules of type r_4 are applied producing objects s_{ijr} in membrane 3 that codify the existence of a path with length r from state s_i to state s_j , as well as the objects T_r codifying the existence of a recurrence time equal to r. Simultaneously, it is checked if there exists a state s_j and a natural number m_0 such that $p_{ij}^{(m_0)} > 0$, for all states s_i . In that case, an object σ is produced in membrane 2 and the system expels an object YES to the environment.

The third stage is only applied if an object YES has not been expelled to the environment. At this stage, the period of the class is computed and it takes $k + \lceil \frac{k}{2} \rceil$ steps. By applying rules of type r_7 , objects p_r encoding recurrence times smaller than or equal to k, are obtained. Such recurrence times are different from each other. By applying rules of types r_8 and r_9 , the greatest common divisor of

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these times is computed. If the period of the class is equal to 1, then the system sends an object YES to the environment, otherwise, the system expels an object p_n that encodes the period of the class to the environment.

4 Formal Verification

Given a computation \mathcal{C} of the P system $\Pi(P_k)$, for each $m \in \mathbf{N}$ we denote by \mathcal{C}_m the configuration of the system obtained after the execution of m steps. For each label $l \in \{1, 2, 3\}$, we denote by $\mathcal{C}_m(l)$ the multiset of objects contained in membrane l in the configuration \mathcal{C}_m . Besides, we denote by $\mathcal{C}_m(env)$ the content of the environment of the system in the configuration \mathcal{C}_m .

Proposition 1. (First stage) We have the following:

(1) For each m, $1 \le m \le k - 1$, we denote $\psi_m = 1 + k + k^2 + \ldots + k^m =$ $(k^{m+1}-1)/(k-1)$. Then

$$\mathcal{C}_m(1) = \{ \beta_m \ t_{ij}^{k^m \cdot p_{ij}} \ \tau_{ij}^{\psi_{m-1} \cdot p_{ij}} \}.$$

 $(2)\mathcal{C}_k(2) = \{c_0^k, \ s_{ii}, \ \tau_{ij}^{\psi_{k-1} \cdot p_{ij}}, \ t_{ij}^{(k^k) \cdot p_{ij}} \mid 1 \le i, j \le k\}$

Proof. (1) By induction on m.

Let us see the result for m = 1. First, we notice that rule $r_2(0)$ is applicable to configuration \mathcal{C}_0 , so $\beta_1 \in \mathcal{C}_1(1)$. Rule $r_1(ij)$ is applicable to configuration \mathcal{C}_0 if

and only if $p_{ij} = 1$. Hence, $C_1(1) = \{\beta_1 \ t_{ij}^{k \cdot p_{ij}} \ \tau_{ij}^{p_{ij}}\}.$ Let m be such that $1 \le m < k - 1$ and $C_m(1) = \{\beta_m \ t_{ij}^{k^m \cdot p_{ij}} \ \tau_{ij}^{\psi_{m-1} \cdot p_{ij}}\}$. Then, rule $r_2(m)$ is applicable to configuration C_m , so $\beta_{m+1} \in C_{m+1}(1)$. Rule $r_1(ij)$ is applicable to configuration \mathcal{C}_m if and only if $p_{ij} = 1$. Hence, $\mathcal{C}_{m+1}(1) = \{\beta_{m+1} t_{ij}^{k^m \cdot k \cdot p_{ij}} \tau_{ij}^{(\psi_{m-1}+k^m) \cdot p_{ij}}\}.$

(2) From (1), we have $C_{k-1}(1) = \{\beta_{k-1} t_{ij}^{k^{k-1} \cdot p_{ij}} \tau_{ij}^{\psi_{k-2} \cdot p_{ij}}\}$. Next, rule $r_1(ij)$ produces k objects t_{ij} and an object τ_{ij} for each object $t_{ij} \in C_{k-1}(1)$. Moreover, rule r_3 produces k copies of c_0 dissolving membrane 1.

Remark: Let us notice that condition $\tau_{ij} \in C_r(1), 1 \leq r \leq k-1$, means that state s_i is reachable from state s_i .

Lemma 2. For each $i, j, r \ (1 \le i, j, r \le k)$ we have the following:

- The sum of the multiplicities of objects $s_{1j} \dots s_{kj}$ in $\mathcal{C}_{k+r}(2)$ is, at most, k^r .
- There exists, at most, k^{r+1} objects c_r in $\mathcal{C}_{k+r}(2)$. $\tau_{ij}^{(\psi_{k-1}-\psi_{r-1})\cdot p_{ij}} \in \mathcal{C}_{k+r}(2).$

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Proof. By induction on r.

Let us suppose that r = 1, Let i, j be such that $1 \leq i, j \leq k$. From (2) in Proposition 1 we have $C_k(2) = \{c_0^k, s_{ii}, \tau_{ij}^{\psi_{k-1}, p_{ij}}\} \subseteq C_k(2)$. Then, rules $r_4(0, 1, 1), \ldots, r_4(0, k, k)$ must be applied.

If $p_{ij} = 1$, then an object s_{ij} (resp. an object τ_{ij}) is produced (resp. is consumed) by the application of rule $r_4(0, i, i)$ (besides, these objects can only be spent/produced by the application of that rules). Hence, the sum of multiplicities of objects s_{1j}, \ldots, s_{kj} will be $p_{1j} + \ldots + p_{kj} \leq k$, there exists at most k^2 objects c_1 in $\mathcal{C}_{k+1}(2)$, and $\tau_{ij}^{(\psi_{k-1}-1)} \in \mathcal{C}_{k+1}(2)$.

Let $r \geq 1, r < k$, and let us suppose that the result holds for r. Let i, j be such that $1 \leq i, j \leq k$. By the induction hypothesis the sum of the multiplicities of objects s_{1i}, \ldots, s_{ki} in $\mathcal{C}_{k+r}(2)$ is, at most, k^r , there exists, at most, k^{r+1} objects c_r in $\mathcal{C}_{k+r}(2)$, and $\tau_{ij}^{(\psi_{k-1}-\psi_{r-1})\cdot p_{ij}} \in \mathcal{C}_{k+r}(2)$. For each i $(1 \leq i \leq k)$ the rules $r_4(r_{1i}), \ldots, r_4(r_{ki})$ will be applied to configuration $\mathcal{C}_{k+r}(2)$ at most k^r times, so at most k^r objects τ_{ij} will be spent and $k^r \cdot k$ objects c_{r+1} will be produced. Then, there exists at most k^{r+2} objects c_{r+1} in $\mathcal{C}_{k+r+1}(2)$, and $\tau_{ij}^{(\psi_{k-1}-\psi_{r-1}-k^r)\cdot p_{ij}} \in \mathcal{C}_{k+r+1}(2)$.

Moreover, each object s_{iq} $(1 \le q \le k)$ produces, at most, an object s_{ij} in $C_{k+r+1}(2)$. Hence, the sum of multiplicities of s_{1j}, \ldots, s_{kj} in $C_{k+r+1}(2)$ will be, at most, $k^r + \ldots + k^r = k \cdot k^r = k^{r+1}$.

Proposition 2. (Second stage) For each $i, j, r \ (1 \le i, j, r \le k)$ we have:

- (1) Objects s_{ij} and c_r belong to $C_{k+r}(2)$ if and only if there exists a trajectory from state s_i to state s_j with a length r.
- (2) A state s of the Markov chain has a recurrence time r if and only if $T_r \in C_{k+r}(3)$.

Proof. (1) By induction on r.

Let us suppose that r = 1. If $s_{ij}, c_1 \in C_{k+1}(2)$, then rule $r_4(0, i, i)$ must be applied by using objects $c_0, s_{ii}, \tau_{ij} \in C_k(2)$. Then, $p_{ij} = 1$, otherwise $p_{ij} = 0 \Rightarrow \tau_{ij} \notin C_k(2)$ (from Proposition 1).

Let i_0, j_0 $(1 \le i_0, j_0 \le k)$ and let us suppose that there exists a trajectory from state s_{i_0} to state s_{j_0} with a length 1. Then, $p_{i_0j_0} = 1$. From Proposition 1 we deduce that $C_k(2) = \{c_0^k, s_{ii}, \tau_{ij}^{\psi_{k-1} \cdot p_{ij}}, t_{ij}^{(k^k) \cdot p_{ij}} \mid 1 \le i, j \le k\}$, so for each i $(1 \le i \le k)$ rule $r_4(0ii)$ is applied once to configuration $C_k(2)$. Then, $\{c_1, s_{i_0j_0}\} \subseteq C_{k+1}(2)$.

Let $r \geq 1$, r < k, and let us suppose that the result holds for r. Let i, j $(1 \leq i, j \leq k)$ be such that $s_{ij}, c_{r+1} \in \mathcal{C}_{k+r+1}(2)$. On the one hand, rule $r_4(ril)$ has been applied, at least once, to configuration \mathcal{C}_{k+r} by using objects c_r , s_{il} , τ_{lj} (for some $l, 1 \leq l \leq k$). So, $p_{lj} = 1$. On the other hand, c_r , $s_{il} \in \mathcal{C}_{k+r}(2)$. Then, by induction hypothesis we deduce that there exists a trajectory with a length r from state s_i to state s_l . Hence, there exists a trajectory with the length r + 1 from state s_i to state s_j .

Let i_0, j_0 $(1 \le i_0, j_0 \le k)$ and let us suppose that there exists a trajectory from state s_{i_0} to state s_{j_0} with a length r + 1. Then, there exists a trajectory from state s_{i_0} to state s_{n_0} with a length r (for some $n_0, 1 \le n_0 \le k$) such that $p_{n_0j_0} = 1$. From the induction hypothesis we have $s_{i_0n_0}, c_r \in \mathcal{C}_{k+r}(2)$, and from Lemma 2 we deduce that

$$\{\tau_{n_0j}^{(\psi_{k-1}-\psi_{r-1})\cdot p_{n_0j}} \mid 1 \le j \le k\} \subseteq \mathcal{C}_{k+r}(2)$$

Then, by applying rule $r_4(r, i_0, n_0)$ once, we obtain $\{c_{r+1}, s_{i_0j}^{p_{n_0j}} : 1 \leq j \leq k\} \subseteq C_{k+r+1}(2)$. Hence, $s_{i_0j_0} \in C_{k+r+1}(2)$ because of $p_{n_0j_0} = 1$.

(2) Let $r \ (1 \le r \le k)$ be the recurrence time of a state s_i . From (1), we deduce that $s_{ii}, c_r \in \mathcal{C}_{k+r}(2)$. Therefore, rule $r_4(rij)$ has been applied to configuration \mathcal{C}_{k+r-1} , for some $j, 1 \le j \le k$, such that $p_{ji} = 1$, and some object $c_{r-1} \in \mathcal{C}_{k+r-1}(2)$. Then, $T_r^{p_{ji}} = T_r \in \mathcal{C}_{k+r}(3)$. Let $r \ (1 \le r \le k)$ such that $T_r \in \mathcal{C}_{k+r}(3)$. Then rule $r_4(r-1, i, j)$ has been applied to configuration \mathcal{C}_{k+r-1} , for some objects s_{ij}, c_{r-1} such that $p_{ji} = 1$. From (1) there exists a trajectory with a length r - 1 from state s_i to state s_j . Hence, there exists a trajectory with a length r from state s_i to state s_i .

Theorem 4. (Output of the system)

Let S be an irreducible homogeneous Markov chain of order k. Let $\alpha = 3k + \lceil \frac{k}{2} \rceil$. We have the following:

- (1) The class S is aperiodic if and only if there exists $r \ (1 \le r \le \alpha k)$ such that configuration C_{k+r+2} of $\Pi(P_k)$ is a halting configuration and $C_{k+r+2}(env) = \{YES\}.$
- (2) The class S is periodic with period equal to n > 1 if and only if configuration $C_{\alpha+2}$ of $\Pi(P_k)$ is a halting configuration and $C_{\alpha+2}(env) = \{p_n\}.$

Proof. Let S be an irreducible homogeneous Markov chain.

- (1) Let us suppose that S is aperiodic. From Theorem 3, there exists a state s_{j_0} and a natural number q > 0 such that $\forall i \ (1 \le i \le k \Rightarrow p_{ij_0}^{(q)} > 0)$. Then, for each $i, \ 1 \le i \le k$, there exists a trajectory with a length q from state s_i to state s_{j_0} .
 - If $q \leq k$, from (1) Proposition 2 we deduce that $s_{1j_0}, \ldots, s_{kj_0}, c_q \in C_{k+q}(2)$. These objects have been produced by the application of rules $r_4(q-1,1,j_1), \ldots, r_4(q-1,k,j_k)$ to configuration C_{k+q-1} , for some j_1, \ldots, j_k such that $p_{j_1,j_0} = \cdots = p_{j_k,j_0} = 1$. So, $s_{1j_0q}, \ldots, s_{kj_0q} \in C_{k+q}(3)$. So, by applying the rule $r_6(j_0,q)$ to configuration C_{k+q} , we have $\{yes\} \in C_{k+q+1}(4)$ and $\sigma \in C_{k+q+1}(2)$. At the next step, rules r_5 and r_{13} are applied. Then, $C_{k+q+2}(env) = \{YES\}$, membrane 2 is dissolved and the system halts.
 - If q > k, then any rule of the type r_6 is not applicable. From Proposition 2 we have encoded the recurrence times (smaller than or equal to k) in membrane 3 by objects T. Then, some rule of the type r_7 produces objects p corresponding to objects T. Next, by applying suitable rules r_8 and r_9

we compute the greatest common divisor of these recurrence times (from Theorem 1 we know that g.c.d. is equal to the period of the class). From the aperiodicity of the class S, we deduce that object p_1 belongs to $C_{\alpha}(3)$. Then, the rule r_{12} produces an object yes in $C_{\alpha+1}(4)$, and we obtain that $C_{\alpha+2}(env) = \{YES\}$ by applying the rule r_{13} . Then, the system halts.

Let us suppose that there exists $r \ (1 \le r \le \alpha - k)$ such that configuration C_{k+r+2} is a halting configuration and $C_{k+r+2}(env) = \{YES\}$. Then, rule r_{13} has been applied to configuration $C_{k+r+1}(4)$, and $yes \in C_{k+r+1}(4)$.

- If $r \leq k$, then the rule $r_6(jr)$ (for some $j, 1 \leq j \leq k$) has been applied to configuration \mathcal{C}_{k+r} , with $s_{1jr}, \ldots, s_{kjr} \in \mathcal{C}_{k+r}(3)$, and $s_{1j}, \ldots, s_{kj}, c_r \in \mathcal{C}_{k+r}(2)$. From (1) in Proposition 2, there exists a trajectory with a length r from state s_i to state s_j , for each i $(1 \leq i \leq k)$. From Theorem 3 we conclude that class S is aperiodic.
- If r > k, object yes has been sent to membrane 4 by applying the rule r_{12} using objects d_{α} and p_1 . But object p_1 has been produced by the iterated application of rules r_8 and r_9 . As these rules compute the greatest common divisor of recurrence times, we deduce that the period of S is equal to 1.
- (2) Now, let us suppose that the period of S is n > 1. From Theorem 3 we deduce that for each j, $1 \le j \le k$, and for each n' > 0 there exists i, $1 \le i \le k$, such that $p_{ij}^{(n')} = 0$. From (1) in Proposition 2 we have $\{s_{ij}, c_{n'}\} \not\subseteq C_{k+n'}(2)$. So, $s_{ijn'} \notin C_{k+n'}(3)$ and any rule of the type r_6 is applicable to configuration $C_{k+n'+1}$. Next, rules of type r_7, r_8, r_9 compute the g.c.d. of the recurrence times. Finally, object p_n is sent to the environment after $\alpha + 2$ steps by applying rules r_{11} and r_{14} . Then, the system halts.

Let us suppose that configuration $C_{\alpha+2}$ is a halting configuration and $C_{\alpha+2}(env) = \{p_n\}$. Then, any rule of the type r_6 will not be applied, so rules r_7 , r_8 , and r_9 will be applied computing the g.c.d of the recurrence times (smaller than or equal to k) of states s_i . Hence, class S is periodic and its period is equal to n.

5 Results and Discussions

In [2] a P system was constructed which allows us to classify the states of a Markov chain. Thus, that P system can be adapted to characterize the aperiodicity of such a chain. Specifically, if $P_k = (p_{ij})_{1 \le i,j \le k}$ is the Boolean matrix associated with the states of a recurrent class of a finite and homogeneous Markov chain of order k, then we define the system

$$\Pi'(P_k) = (\Gamma'(P_k), \mu'(P_k), \mathcal{M'}_1, \mathcal{M'}_2, \mathcal{M'}_3, \mathcal{M'}_4, R', \rho')$$

as follows:

• Working alphabet:

$$\Gamma'(P_k) = \{ d_{ij}, t_{ij} \mid 1 \le i, j \le k, \} \cup \{ c_r \mid 0 \le r \le 2k + 2 \} \cup \{ t_{ijur} \mid 1 \le i, j, u \le k, 0 \le r \le k \} \cup \{ \beta_i \mid 0 \le i \le \alpha + 1 \} \cup \{ s_{ijr} \mid 1 \le i, j \le k, 0 \le r \le k \} \cup \{ A_{i1}, R_{ij} \mid 1 \le i, j \le k \}$$

- where $\gamma = 2k + 4 + \lceil \lg_2 k \rceil + \frac{(k-1)(k+2)}{2}$. Membrane structure: $\mu'(P_k) = [\lceil \lceil \rceil | 4 \rceil_3 \rceil_2 \rceil_1$. •
- Initial multisets: •

•

 $\begin{aligned} \mathcal{M}'_1 &= \emptyset; \ \mathcal{M}'_2 = \{\beta_0\}; \ \mathcal{M}'_3 = \{c_0\}; \\ \mathcal{M}'_4 &= \{s_{ii0} \quad t_{ij}^{p_{ij}(k-1)} \mid 1 \leq i,j \leq k\}. \end{aligned} \\ \text{The set } R \text{ of evolution rules consists of the following rules:} \end{aligned}$

$$\begin{array}{lll} - & \text{Rules in the skin membrane labeled by 1:} \\ r_1 = \{d_{ip} \to (R_{ip}, out) \mid 1 \leq i \leq k, \ 1$$

- The partial order relation ρ' over R' consists of the following relations on the • rules of R':
 - Priority relation in the skin membrane: \emptyset . _
 - Priority relation in the membrane labeled by 2: $\{r_4 > r_5\}$
 - Priority relation in the membranes labeled by 3: \emptyset . _
 - Priority relation in membrane 4: \emptyset .

In order to study the efficiency of the P system $\Pi(P_k)$ constructed in this work, we will compare the results with those obtained by the P system $\Pi'(P_k)$ described above. For that purpose, a comparative analysis of the computational resources required in both P systems is given firstly. Secondly, an analysis of the times of execution obtained on designed simulators for both P systems with some case studies is presented.

5.1 Computational Resources Required

The resources required initially to construct the systems $\Pi(P_k)$ and $\Pi'(P_k)$, and the number of steps taken for the systems, are the following:

	$\Pi(P_k)$	$\Pi'(P_k)$
Size of the alphabet	$\Theta(k^3)$	$\Theta(k^4)$
Initial number of membranes	4	4
Sum of the sizes of initial multisets	$\Theta(k^2)$	$\Theta(k^4)$
Number of rules	$\Theta(k^3)$	$\Theta(k^4)$
Maximal length of a rule	$\Theta(k)$	$\Theta(k)$
Number of priority relations	0	$\Theta(k^2)$
Number of steps	$\Theta(k)$	$\Theta(k)$

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In the previous table, let us notice that the amount of resources requested by $\Pi(P_k)$ is smaller than the ones requested by $\Pi'(P_k)$. Indeed, the size of the alphabet and the number of rules pass from power 3 to power 4, and the system $\Pi(P_k)$ has no priority relation. The number of steps is of the same asymptotic order.

5.2 Case Studies

We have designed a simulator for each system $\Pi(P_k)$ and $\Pi'(P_k)$. These simulators have been written in C++ language and they have been executed on a Pentium 4 computer with 512 Mb RAM and 3.20 GHz.

In both simulators objects t_{ij} have been represented by means of arrays of dimension 2; objects s_{ij} have been represented by vectors of dimension 2 and recurrent times have been represented by one-dimensional vectors.

The simulator of the system $\Pi(P_k)$ generates the trajectories with a length at most $3k+\lceil k/2\rceil$ in a sequential way, keeping the times of recurrence smaller than or equal to k. If assertion (2) in Theorem 3 is fulfilled, the simulator halts displaying the time of execution and the aperiodicity of the Markov chain. Otherwise the simulator computes the g.c.d. of the recurrence times obtained where all of them are different.

Similarly, a simulator for the system $\Pi'(P_k)$ has been implemented. The main difference with respect to the previously mentioned one is that it can keep more than a copy of the times of recurrence. All trajectories of the Markov chain with a length smaller than or equal to 3(k-1) and their recurrence time are computed. Then the g.c.d. of these times is obtained.

When the Markov chain is aperiodic, the P system $\Pi(P_k)$ can finish before all trajectories with a length $3k + \lceil k/2 \rceil$ are computed. In case it is necessary to calculate the period, bearing in mind that all recurrence times are different, system $\Pi(P_k)$ is faster than $\Pi'(P_k)$ in computing the g.c.d. of these times.

When the Markov chain is periodic the length of the trajectories computed by $\Pi(P_k)$ are longer than those computed by $\Pi'(P_k)$. Nonetheless, in order to compute the period, recurrence times used in $\Pi(P_k)$ are all different.

The simulators designed have been executed on eight recurrent Markov chains with 100 states. Four of these Markov chains are periodic and the others are aperiodic. Table 1 shows the values equal to 1 of the adjacency matrix of the graph associated with the recurrent Markov chains. The execution times are described in Table 2.

Example			
1	$p_{i,i+1} = 1$	$1 \le i \le 99$	
	$p_{100,1} = 1$		
2	$p_{i,i+1} = 1$	$1 \le i \le 99$	
	$p_{i,1} = 1$	$1 \leq i \leq 100$	
3	$p_{10j+i,10j+i+1} = 1$	$1 \le i \le 9$	$0 \le j \le 9$
	$p_{10j,10j-9} = 1$	$1 \leq j \leq 10$	_• -
	$p_{10j+1,10j+11} = 1$		
	$p_{91,1} = 1$	_ v _	
4	$p_{10j+i,10j+i+1} = 1$	$1 \le i \le 9$	0 < j < 9
	$p_{10j,10j-9} = 1$		_ 2 _
	$p_{10j+1,10j+11} = 1$	0 < j < 8	
	$p_{91,1} = 1$		
	$p_{1,1} = 1$		
5	$p_{10j+i,10j+i+1} = 1$	$1 \le i \le 9$	$0 \le i \le 9$
	$p_{10j,10j-9} = 1$		° _ J _ °
	$p_{10j+1,10j+11} = 1$	0 < i < 8	
	$p_{91,1} = 1$	° _ J _ °	
	$p_{2,2} = 1$		
6	$\frac{p_{2,2}}{p_{5j+i,5j+i+1}} = 1$	$1 \le i \le 4$	0 < i < 19
	$p_{5j,5j-4} = 1$		0 _ J _ 10
	$p_{5j,5j-4} = 1$ $p_{5j+1,5j+6} = 1$		
		$0 \leq j \leq 10$	
7	$p_{96,1} = 1$	$1 \le i \le 100$	
1	$p_{i,i+1} = 1$	$1 \le i \le 100$ $1 < i < 100$	
	1 - 1		
		$0 \le i \le 32$	
8	$p_{i,i+1} = 1$	$1 \le i \le 100$	
	$p_{i+1,i} = 1$	$1 \leq i \leq 100$	
	$p_{1+3i,4+3i} = 1$	$0 \le i \le 32$	
	$p_{1,1} = 1$		

Table 1. Adjacency values of the examples

6 Conclusions

Markov chains have applications in different fields such as physics, economics, biology, statistics, social sciences... In these applications it is important to know whether the Markov chain associated with the process is convergent or not. When the Markov chain is aperiodic, the transition matrix converges and the process becomes stable. In other cases, the process does not reach an equilibrium.

In this work, a characterization of the aperiodicity of a Markov chain has been given in terms of the existence of a state reachable from any other state. Based on this property, a computational P system has been constructed that allows us to know whether the Markov chain is aperiodic and calculate its period if not. A formal verification of P system using the methodology based on the search of invariant formulae has been presented.

Example	period	Previous	New
1	100	0	0
2	1	146	0
3	10	0	0
4	1	122	35
5	1	1	2
6	5	11	20
7	2	381	169
8	1	1101	104

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Table 2. Observed run times

In [2], every finite and homogeneous Markov chain has associated a P system that provides a classification of its recurrent classes. That P system can be adapted to study the aperiodicity of a Markov chain and then its period can be calculated. The solution presented in this work improves the solution derived from the P system described in [2]. For that purpose, simulators have been constructed for these P systems and the respective times of execution on eight examples have been analyzed.

For the computational study of the aperiodicity of a Markov chain it would be interesting to design new P systems that incorporate additional features such as electrical charges, active membranes, etc. and that improve quantitatively the amount of computational resources used.

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